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**SUMMIT**

USC  
Viterbi  
School of Engineering

Behnam Jafarpour

Sep 30 – Oct 1  
2021

1

USC-Energi Simulation Center for Advanced Reservoir Characterization and Forecasting

**Dynamic Characterization Research**  
Behnam Jafarpour

**USC**  
**Viterbi**  
School of Engineering

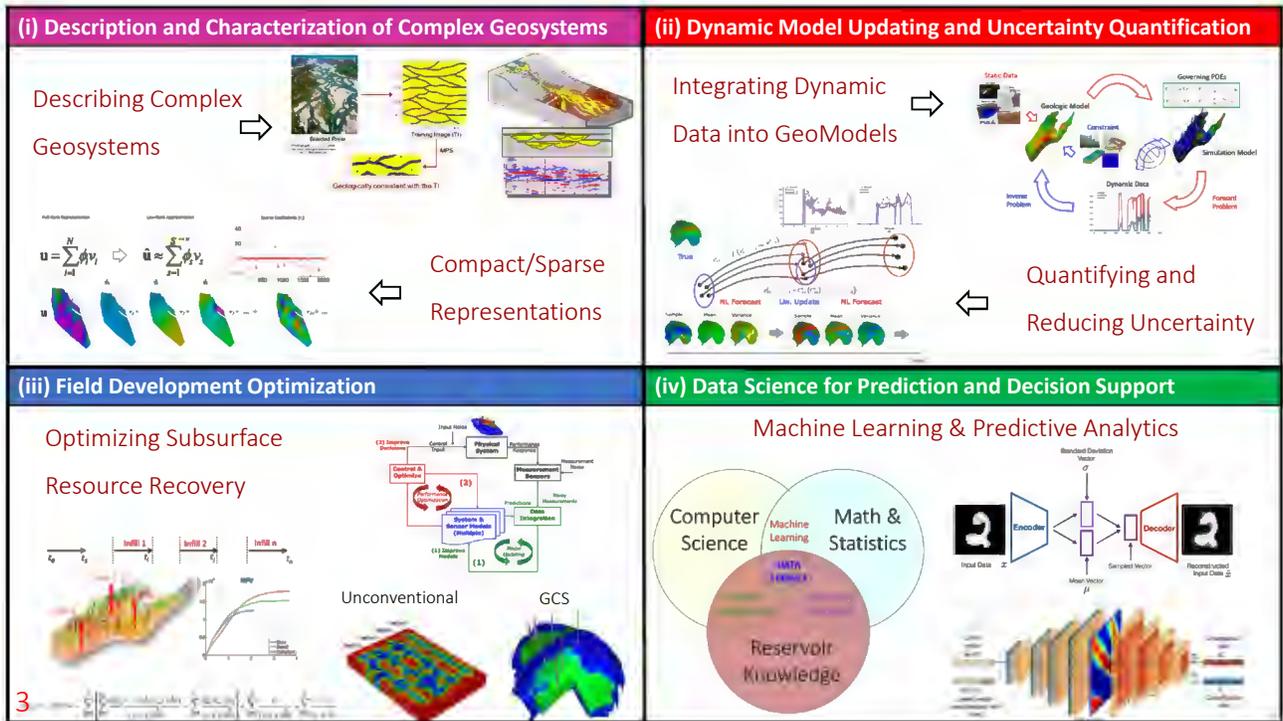
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Center for  
Advanced Reservoir  
Characterization & Forecasting

Annual Energi Simulation Summit (Online), September 31-October 1, 2021

Creating a more sustainable energy future through simulation research

2

2



3




Advanced Reservoir Characterization and Forecasting

## Dynamic Neural Network Models for Prediction and Optimization of Geothermal Energy Production

Behnam Jafarpour

Annual Energi Simulation Summit  
Sep 31-Oct 1, 2021  
Online Webinar

4

Creating a more sustainable energy future through simulation research

4

## Research Thrust Areas

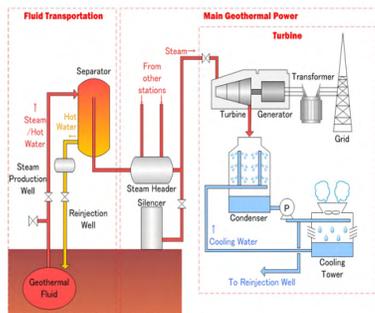
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### Power Plant:

Fault prediction/diagnosis and model predictive control for efficient automation of power plant operations

### Power Plant

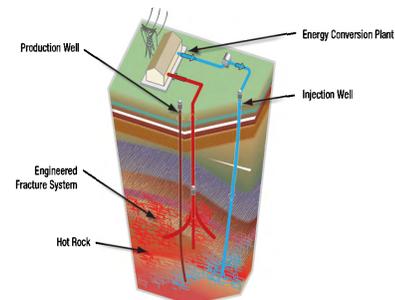


5

### Reservoir/Resource:

Customized predictive analytics and closed-loop control for geothermal reservoirs

### Reservoir/Resource



5

## USC-Cyrq Energy Inc. Collaboration

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### USC Team

- **Behnam Jafarpour, PI** (Professor, CHE/ECE/CEE)  
*Deep learning for subsurface energy systems*
- **Robert Young** (Associate Professor of Chemical Engineering Practice)  
*Process modeling and control*
- **Anyue Jiang** (PhD Student, Chemical Engineering)  
*Recurrent neural networks for multi-physics data*
- **Zhen Qin** (PhD Student, Petroleum Engineering)  
*Optimization and control with recurrent neural networks*
- **Yingxiang (Sam) Liu** (PhD Student, Electrical and Computer Engineering)  
*Anomaly detection and predictive control based on neural network models*
- **Wei Ling** (PhD Student, Chemical Engineering)  
*Dynamic deep neural network models for power plant operations*

6

### Cyrq Energy Inc. Team

- **Trenton Cladouhos** (PhD)  
*VP of Resource*
- **Jalal Zia** (PhD)  
*VP of Engineering*
- **Dave Faulder**  
*Director of Reservoir Engineering*
- **Michael Swyer**  
*Senior Geoscientist*
- **Ian Spanswick**  
*President (O2RC Solutions)*

6

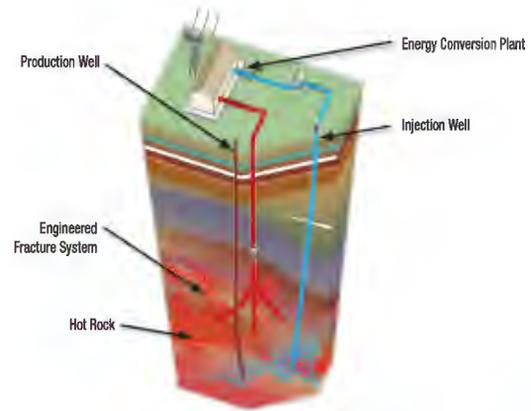
# Reservoir/Resource



USC Viterbi School of Engineering

**Reservoir/Resource:**  
Customized predictive analytics and closed-loop control for geothermal reservoirs

## Reservoir/Resource



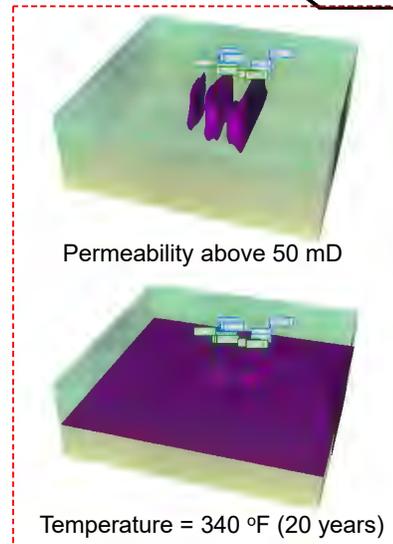
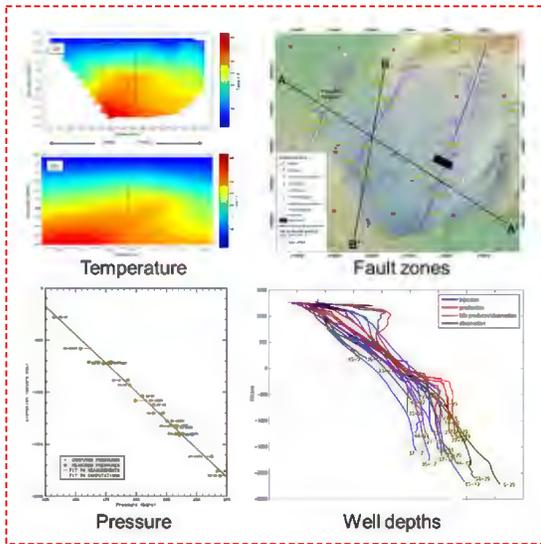
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# Field Data and Simulation Model



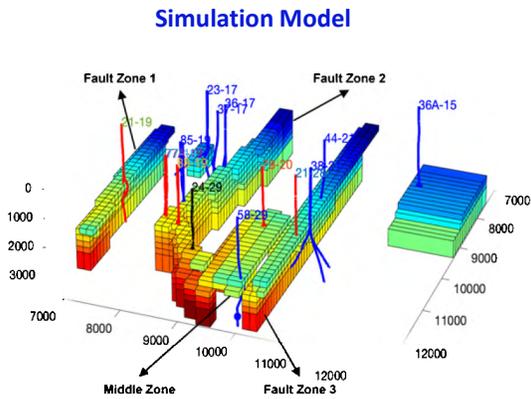
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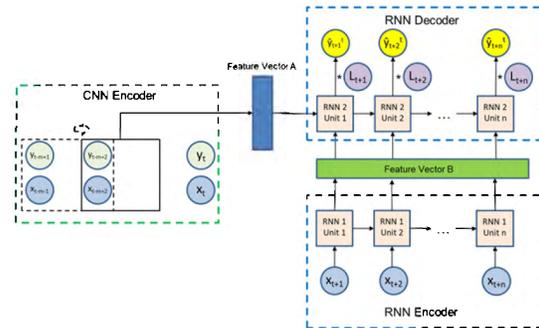
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# Simulation & Deep Learning Model



## Deep Learning Model

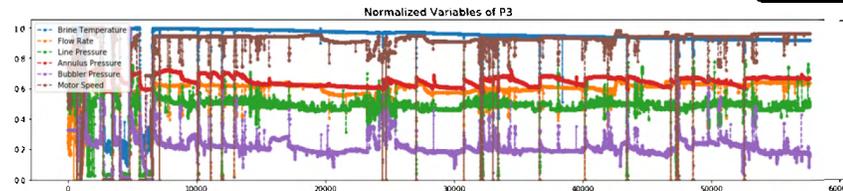


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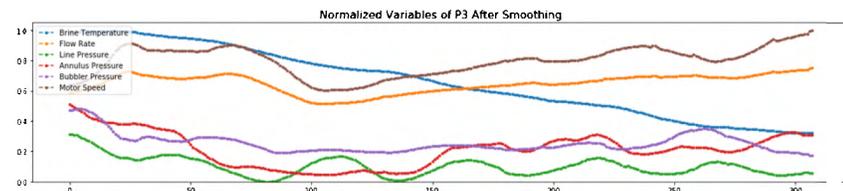
# Short-Term and Long-Term Predictions



Raw hourly data for short-term prediction



Smoothed weekly data for long-term prediction



High frequency data  
 Low frequency feature  
 Variability introduced by shut-in



Long sequences  
 Possible long-term predictions  
 Steps that should be ignored

10

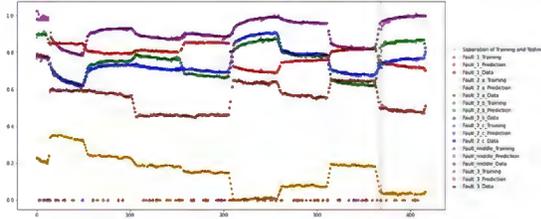
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# Short-Term Predictions

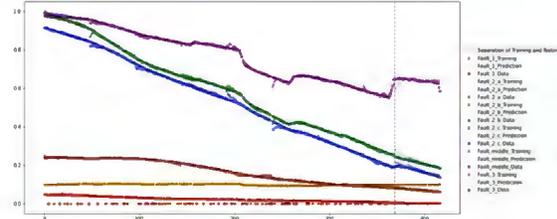


Short Term Predictions (Using historical data)

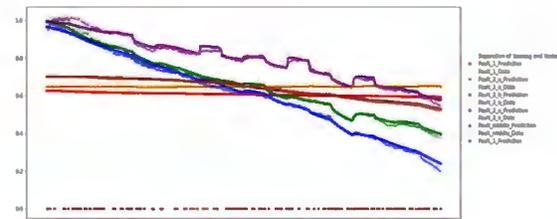
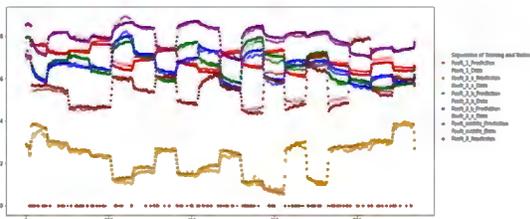
Producer BHP



Producer Enthalpy



Long-Term Predictions (using ensemble of simulated historical data)



11

11

# Field Performance Optimization



**Objective Functions:**

- Net Power Generated,
- Min-max Temperature changes,
- Min-Average Temperature changes

$$E_{net} = \sum_t^T E_{gross}(kWh) - E_{pumps}(kWh)$$

$$J(\mathbf{u}) := \frac{1}{t} \sum_{\tau}^t \max \Delta T(\tau, \mathbf{u})$$

$$J(\mathbf{u}) := \frac{1}{Nt} \cdot \sum_p^N \sum_{\tau}^t (\Delta T(\tau, \mathbf{u}))$$

**Control Variables:**

- Injection/Production Rate

**Constraints:**

- Total production rate
- Mass balance (Production = Injection)
- Upper and lower bounds

$$\begin{aligned} & \min_{\mathbf{u}} J(t, \mathbf{u}) \\ \text{s. t.} & \sum_p^N \mathbf{u}_{prod,p} = \mathbf{Q}_{prod} \\ & \sum_p^N \mathbf{u}_{prod,p} = \sum_i^M \mathbf{u}_{inj,i} \\ & \mathbf{LB} \leq \mathbf{u} \leq \mathbf{UB} \end{aligned}$$

12

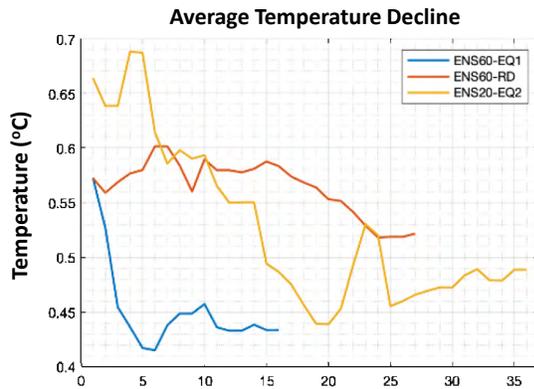
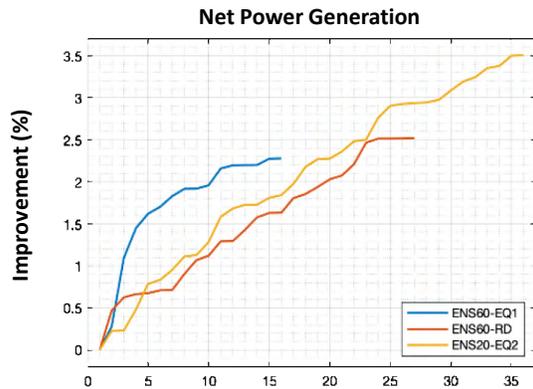
12

## Objective Function



$$\text{Max Net Power: } \max J(\mathbf{u}) := \sum_{\tau}^t E_{\text{gross}}(\text{kWh}) - E_{\text{pump}}(\text{kWh})$$

$$\text{Min Avg dT: } \min J(\mathbf{u}) := \frac{1}{Nt} \cdot \sum_p^N \sum_{\tau}^t (\Delta T(\tau, \mathbf{u}))$$

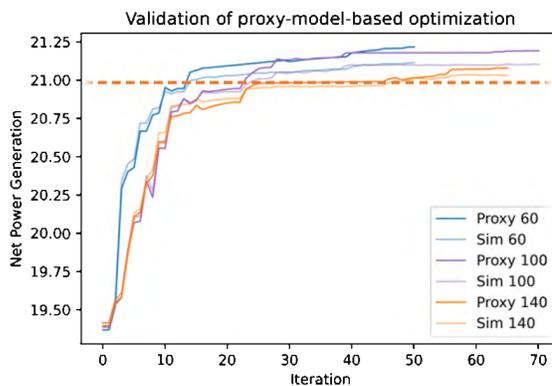


Maximizing Net Power Generation → improved temperature decline (sustainable production)

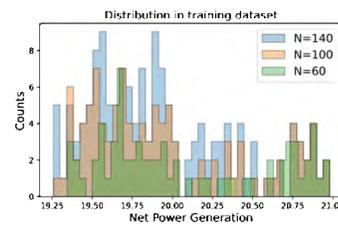
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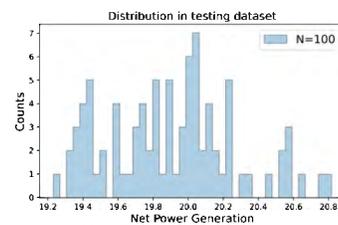
## Proxy-Based Optimization



Maximum value in training dataset



Training dataset



Testing dataset

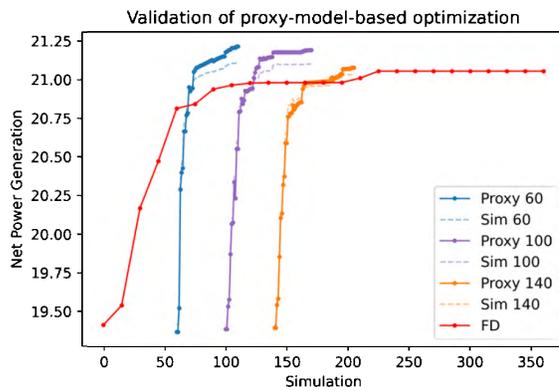
### Comments:

- Monitor: Acceptable prediction during optimization
- Extrapolation: Optimal value higher than the maximum value in training dataset.

14

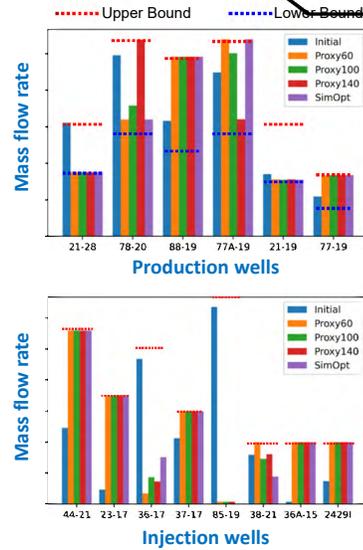
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# Proxy-Based Optimization



**Comments:**

- Validation: simulation-based optimization
- Controls & objective: converge to same values.
- Computational cost: Proxy: 60~140. Sim: 360



15

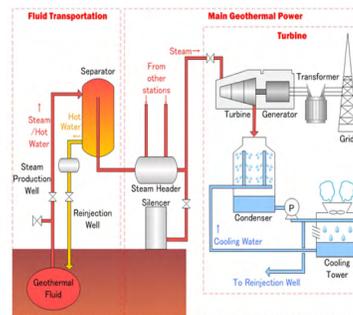
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# Power Plant



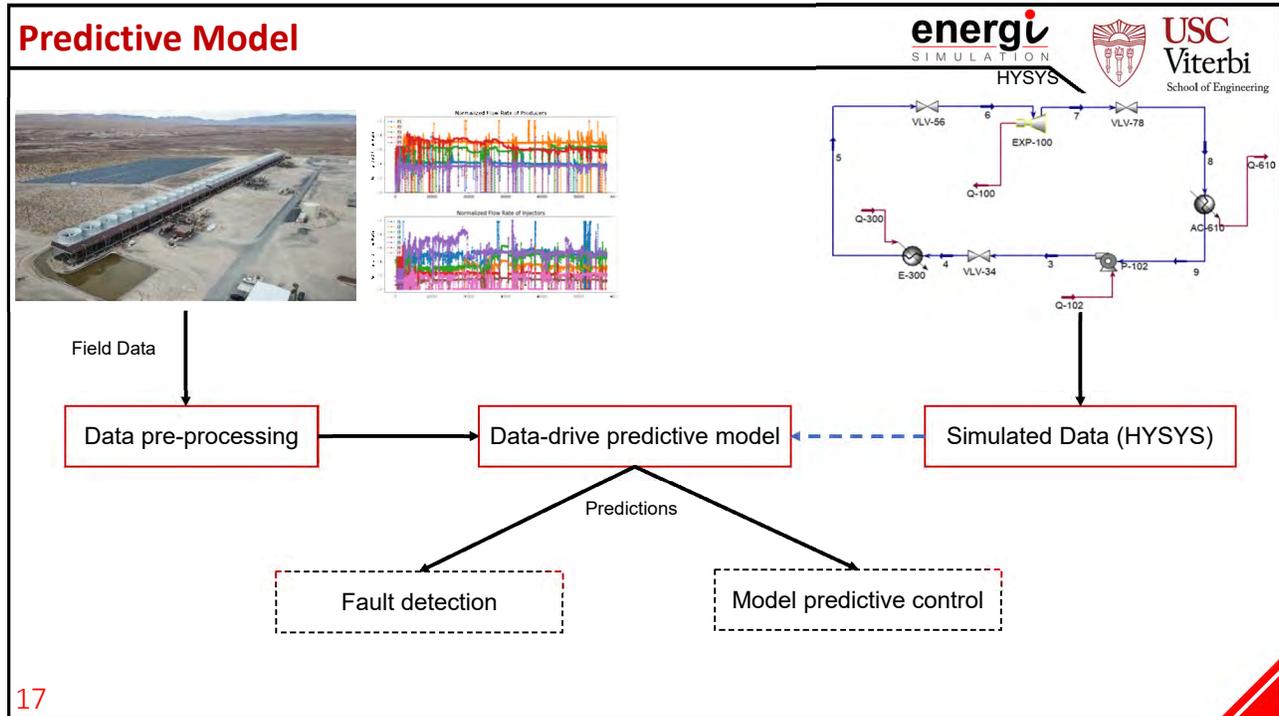
**Power Plant:**  
 Fault prediction/diagnosis and model predictive control for efficient automation of power plant operations

## Power Plant



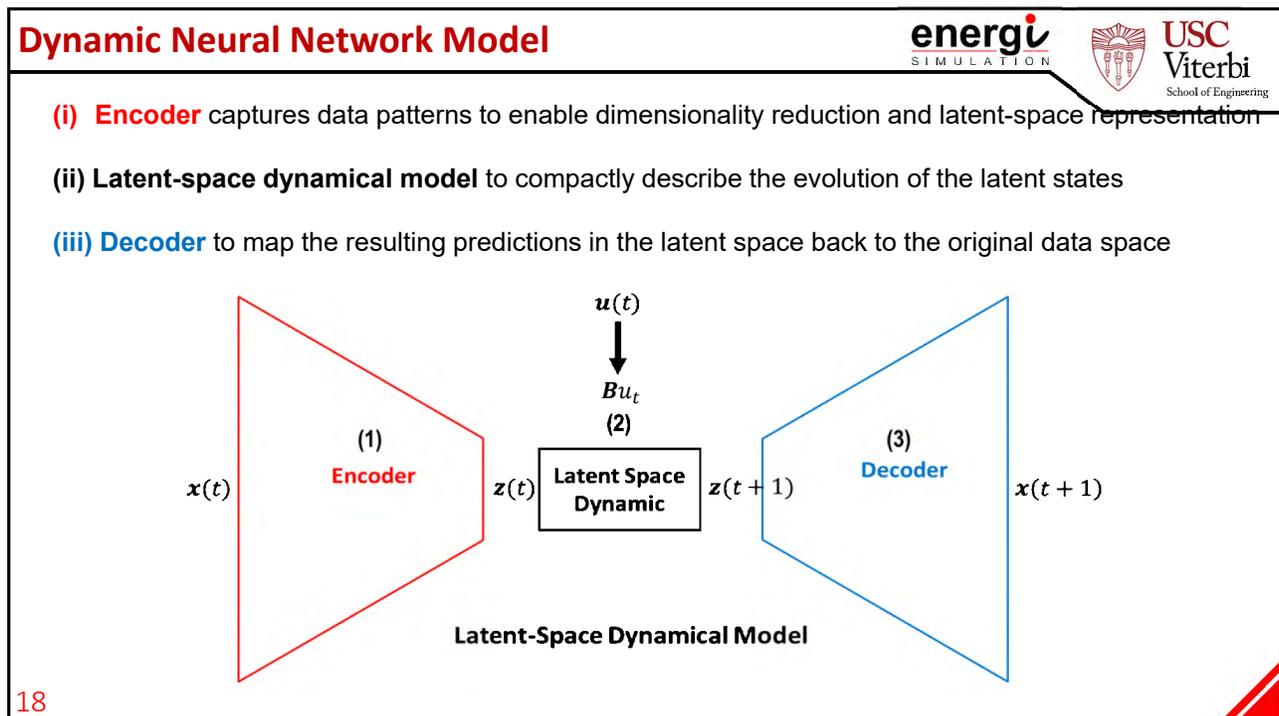
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18

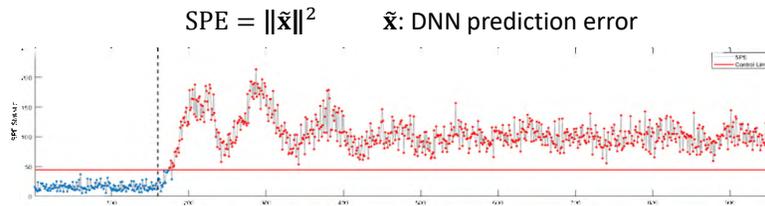
18

## Fault Detection: Monitoring Index and Limits



### Statistical Monitoring Index

→ Squared Prediction Error (SPE) statistic, rooted in Principal Component Analysis



### Control Limit

→ The sample is considered normal if its SPE is below a certain threshold  $\delta_\alpha^2$

→  $\delta_\alpha^2$  is the upper limit of SPE with a confidence level of  $\alpha$  in a  $\chi^2$  distribution

$$\delta_\alpha^2 = g\chi_{h;\alpha}^2 \quad \text{where } g = \frac{\theta_2}{\theta_1}, \quad h = \frac{\theta_1^2}{\theta_2}, \quad \theta_i = \sum_{j=l+1}^m \lambda_j^i$$

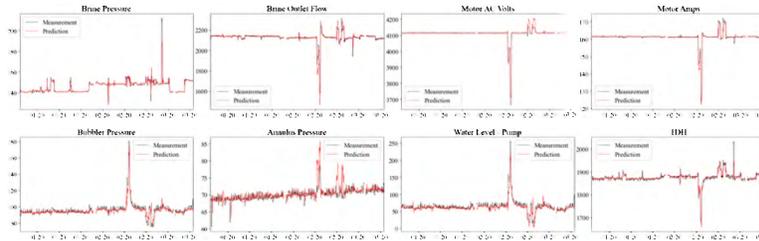
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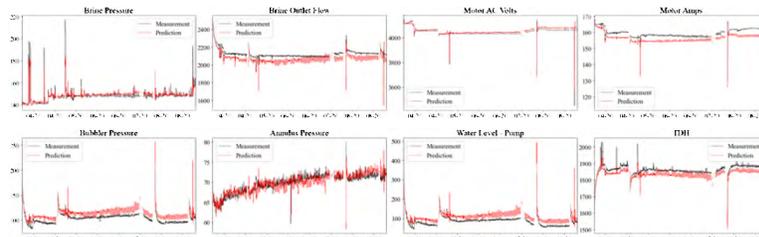
## Validation with Pump Data



### Pump data: Before maintenance



### Pump data: After maintenance



20

20

## Model Predictive Control (MPC)

Objective: Using the DNN model for Model Predictive Control (MPC)

MPC Example

Minimize the mismatch to the reference set point

Constraints represent physical actuator limits and safety bounds

r: reference set points  
d: disturbance  
u: control input  
x: state  
y: output

MPC optimizer predict the future performance and the optimal control on next step over the predict horizon

Some system states can not be directly measured

MPC Diagram

21

21

## Overall Workflow

Binary Power Plant

Overall Workflow

22

22

11

## Examples



### Organic Rankine Cycle Power Plant



**Measurements: 23 variables**

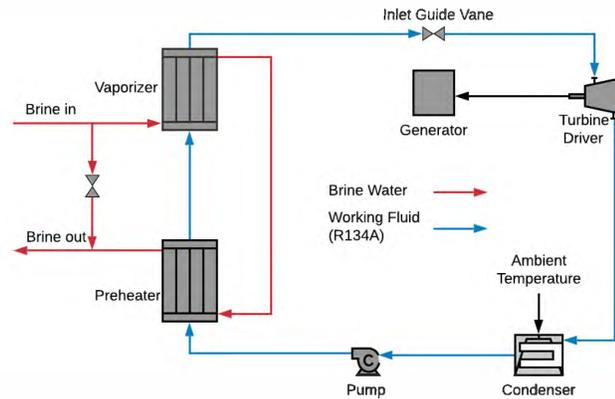
**Control variables:**

- Condenser fan speed
- Inlet guide vanes (IGV) set point
- Working fluid pump speed

**Disturbances:**

- Ambient temperature
- Inlet brine variable

### Organic Rankine Cycle Diagram



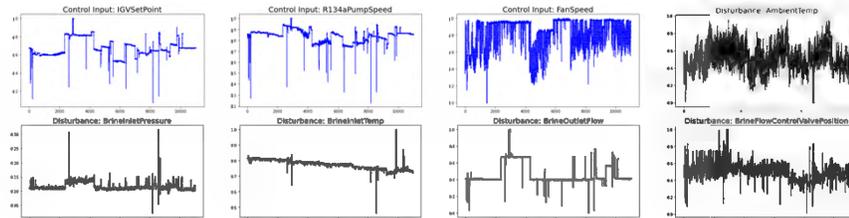
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## Predictive Model



- Data resolution: hourly
- Training: 5000 samples
- Validation: 1000 samples
- Testing: 3000 samples

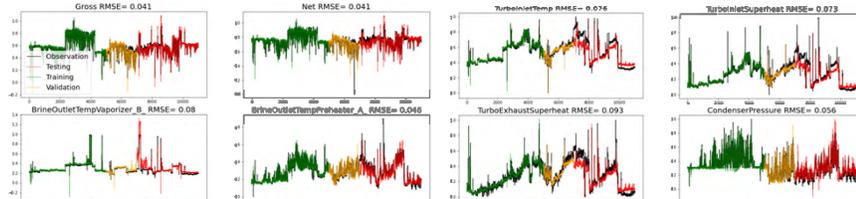


Control and disturbances

**Model:**

- Past samples  $k = 3$ ,
- Latent variable  $n_z = 6$ ,
- Prediction horizon  $p = 12$

**RMSE = 0.07**



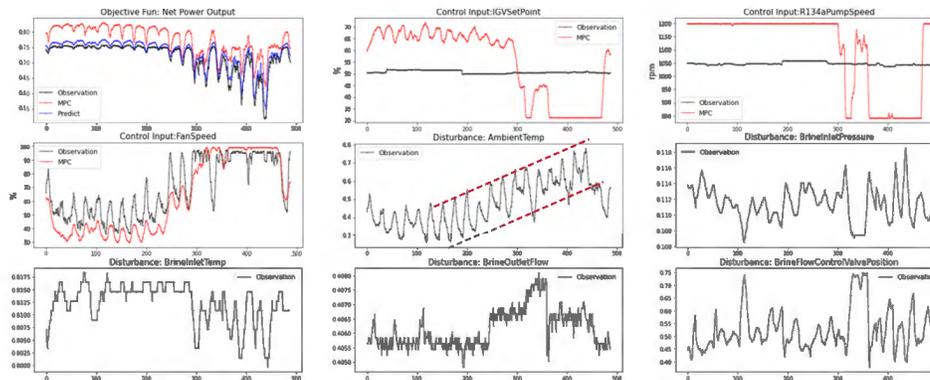
12 step ahead prediction for 23 variables

24

24

## Preliminary Results

Average improvement in **net power production** is **4.0%**



MPC tries to **increase pump speed, open the IGV, and decrease condenser fan speed** when the **ambient temperature** is relatively low.

25

25

## Preliminary Conclusions

Developed and applied deep learning-based prediction models for:

- 1) Energy production prediction and optimization ([Reservoir](#))
- 2) Fault detection and MPC application ([Power Plant](#))

**General observations:**

- Deep learning models are [easy to develop and deploy](#) for field applications
- [Short-term](#) predictions with historical field data are generally acceptable
- May need additional data or constraints to enable [long-term predictions](#)
- [Extrapolation](#) (prediction out of training range) is challenging, need for physics

26

26

# Acknowledgement



27

27